

HDR-Nets 2020

# MoGAN: GAN based Next PoA Selection for Proactive Mobility Management

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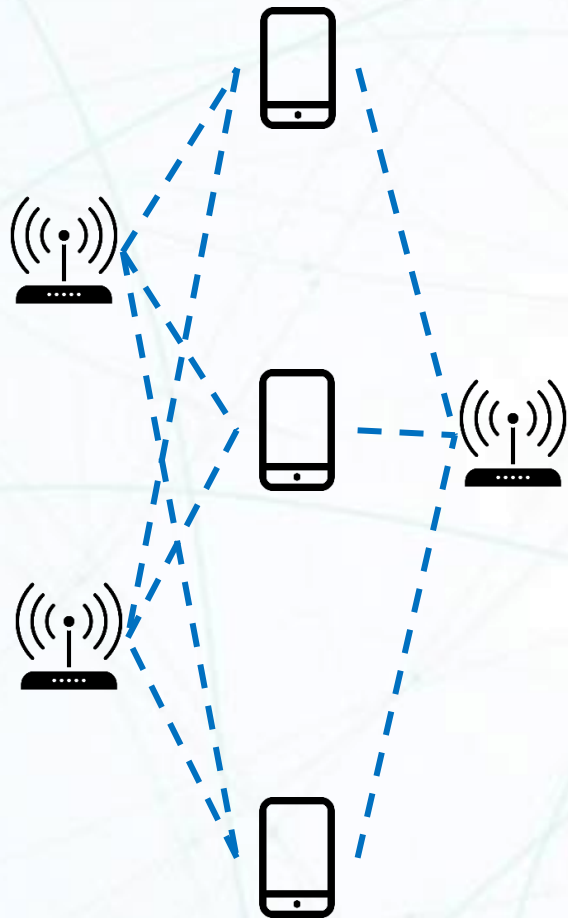
- Problem Statement
- Deep Learning Approaches for Prediction
- MoGAN
- Evaluations
- Conclusions

# Problem Statement



- Requirement
  - Sub 10ms mobility delay for 5G
- Problem
  - User assisted reactive mobility management in 4G is potential bottleneck for 5G
- Solution
  - **Proactive mobility management**

# Problem Statement



- Requirements of proactive mobility management
  - Next Point of Attachment (PoA) prediction with high accuracy
  - Optimal decision for handover trigger time
- Challenges
  - Dense and Ultra-dense cell deployment in 5G
  - Real-time prediction and decision algorithms
- Solution
  - This work focuses on prediction of next PoA
  - A GAN based next PoA prediction mechanism

- **Recurrent Neural Network (RNN)**

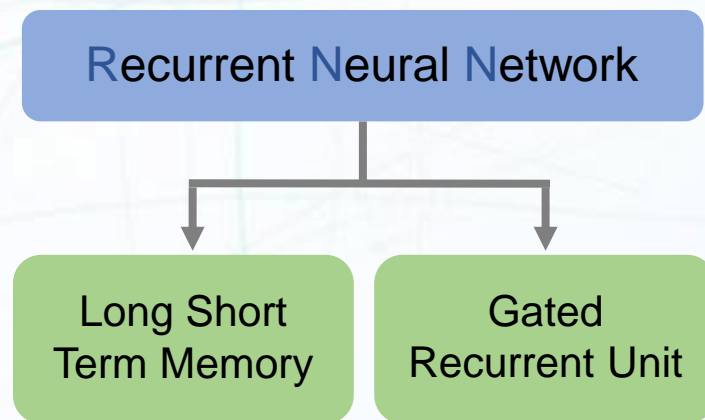
- Pros: Available to capture the feature of continuous data
- Cons: Gradient vanishing problem occurs with long sequence length  
→ Long-term dependency

- **Long Short-Term Memory (LSTM)**

- Pros: Additional cell states enable to save more information of past sequences
- Cons: Complex structure results more computational cost

- **Gated Recurrent Unit (GRU)**

- Computationally less expensive
- Better performance for less complex data



# DL Approaches for Prediction

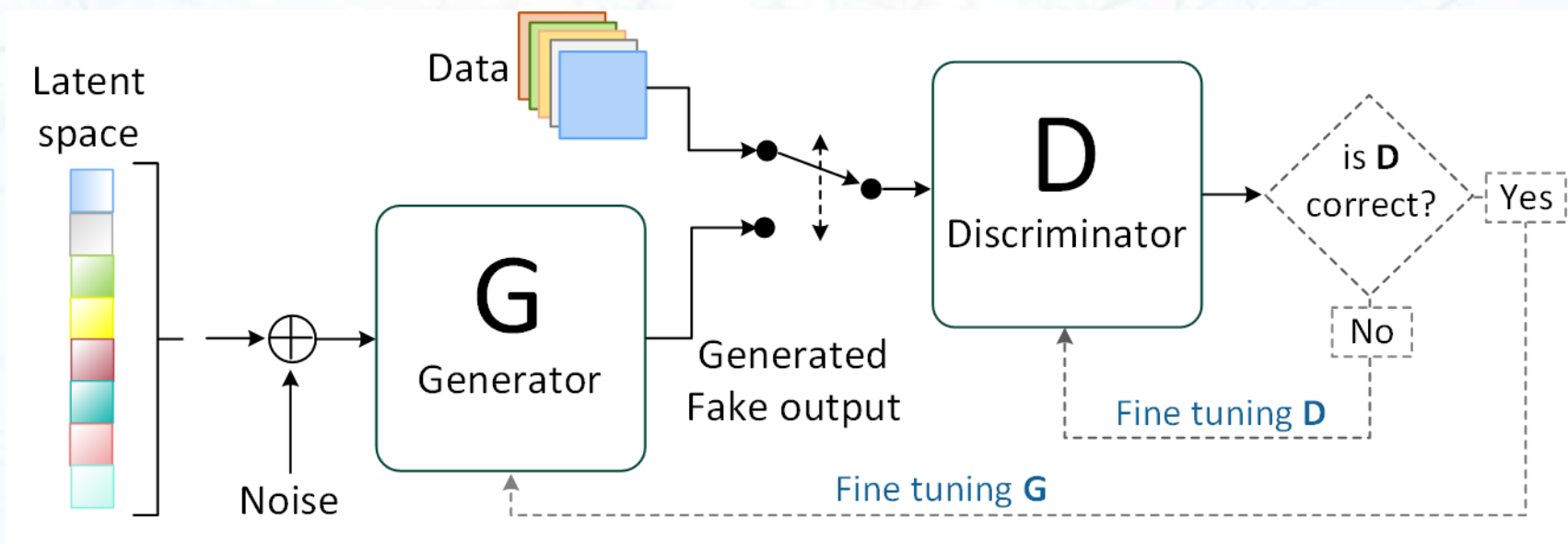


- GAN (Generative Adversarial Network)

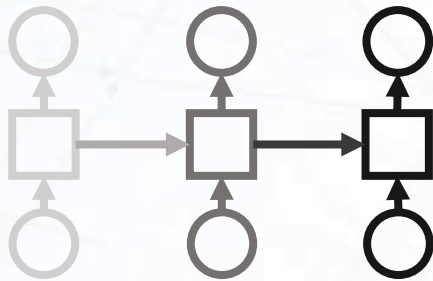
➤ Various usage



- Data generating model
- Classification model
- **Prediction model**

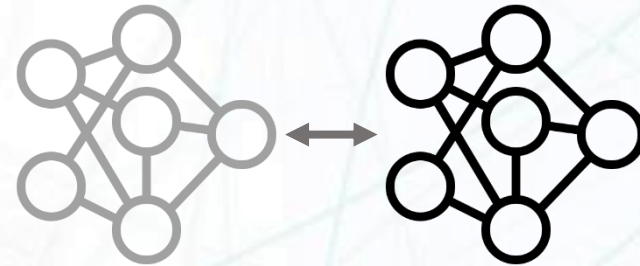


## LSTM



- Usually used for prediction
- Large amount of data is required for training
- Former study achieved 91% of accuracy

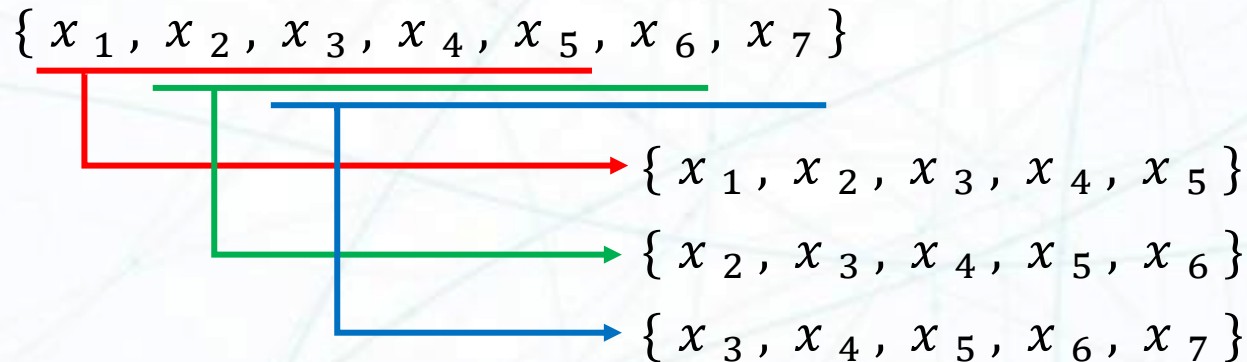
## GAN



- Useful feedback from its adversaries
- Trained to reflect whole distribution of data
- Various types of data are available

- Data preprocessing

- Movement history (Sequence of PoA)
  - Suppose the actual length of sequence is 5
  - Movement history with less than 5 PoAs: ignored
  - Movement history with more than 5 PoAs: divided



- For each PoA → Transform into One-hot vector
  - N-dimensional vector if there are total N points in the data

## ● Architecture

- Model for predicting next PoA of mobile devices
- Learns from the data consisting of previous sequences

## **Generator**

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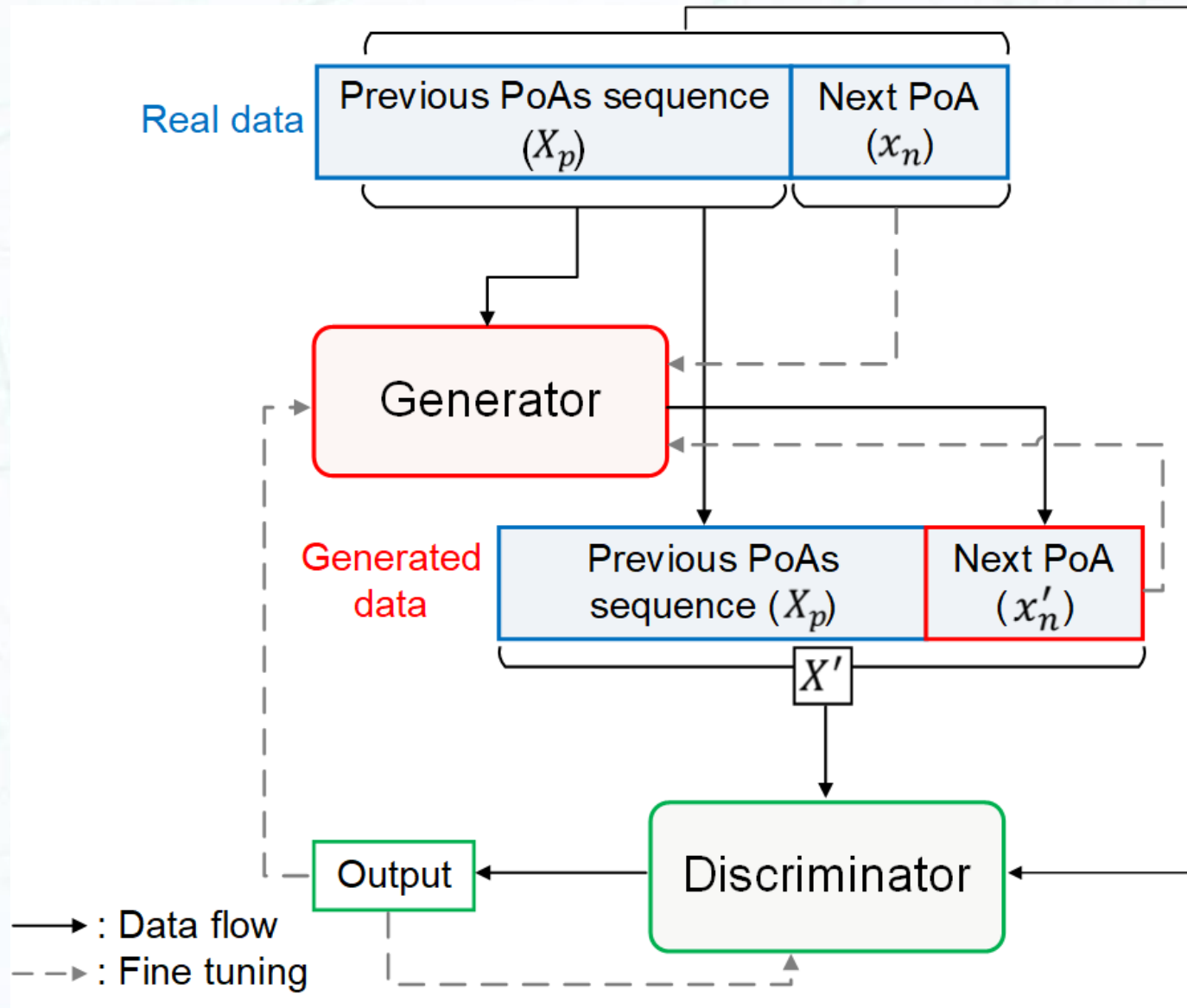
- Learns the distribution of previous PoA connections
- Generates probable next PoA
- Used as prediction model after training completed

## **Discriminator**

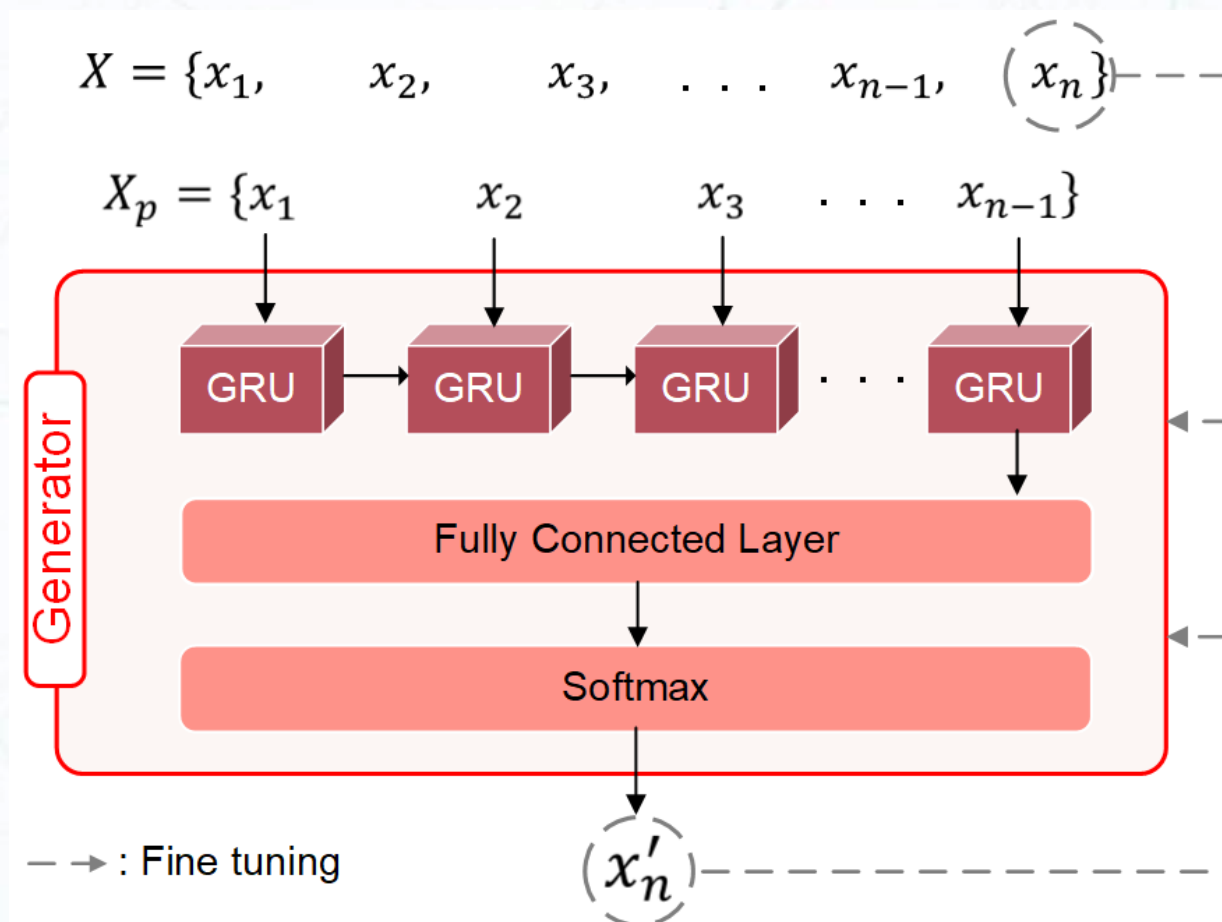
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- Classifies between real PoA sequences and generated ones
- Useful feedback for generator

# MoGAN

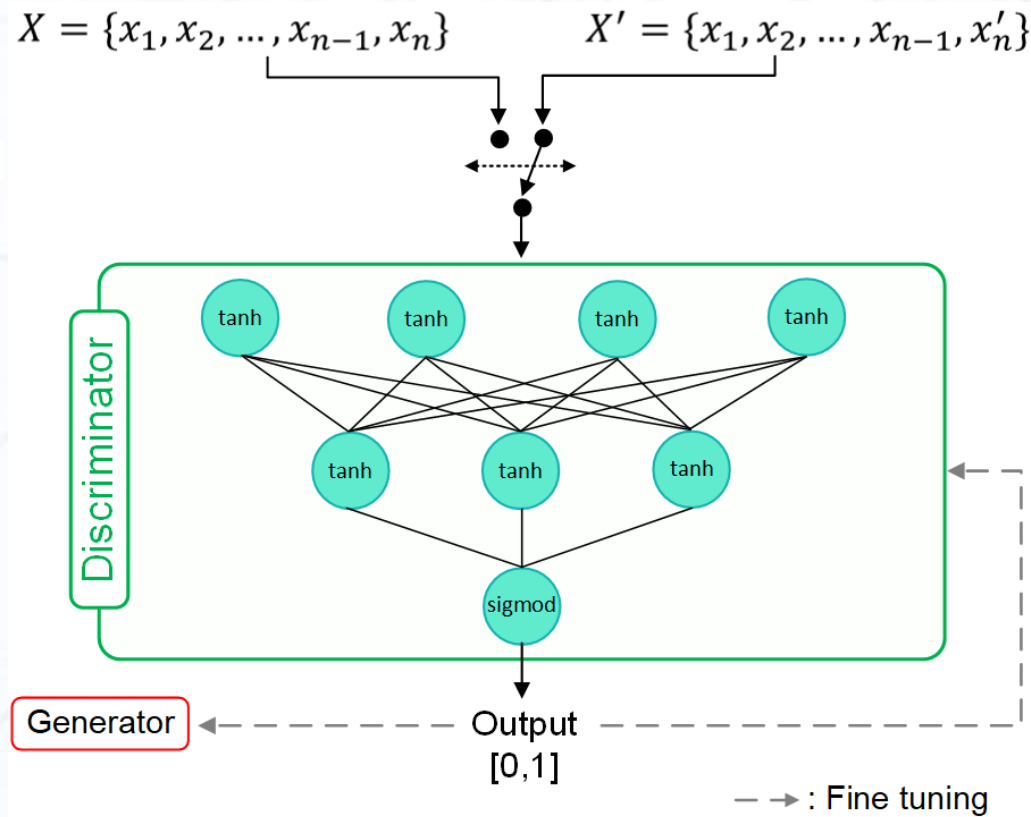


- Structure of generator



- Structure of discriminator

- For classification, FC layer performs better than RNN based structures
  - For recognizing all the properties of structures



- Training procedure of MoGAN

- Error function: Binary cross entropy

$$H(y, y') = -\frac{1}{N} \sum_{i=1}^N (y_i \log(y'_i) + (1 - y_i) \log(1 - y'_i))$$

- $y$  : Expected value,  $y'$  : Predicted value

- Step 1 (Minimax step)

- $\min_{G_\theta} \max_{D_\phi} [H(0, D_\phi(X)) + H(1, D_\phi(X_p + G_\theta(X_p)))]$

- Step 2 (Additional training step for generator)

- $\min_{G_\theta} [H(x_n, G_\theta(X_p))]$

## Algorithm: The training procedure of MoGAN

**Initialize:** Number of total epoch  $n$ , number of Step 2 per epoch  $\alpha$ ,  
randomly initialized weights  $\theta, \phi$  for  $G_\theta, D_\phi$

**Input:**  $X = \{x_1, x_2, \dots, x_{n-1}, x_n\}$

1. Error function  $\leftarrow$  binary cross entropy  $H$
2. for  $n$  do:
3.  $G_\theta(X_p)$  predicts next PoA  $x_n'$
4.  $X' \leftarrow$  Combine  $X_p$  with  $x_n'$
5.  $D\_loss\_real \leftarrow$  Get loss value from  $D$  for real data  $H(0, D_\phi(X))$
6.  $D\_loss\_fake \leftarrow$  Get loss value from  $D$  for generated data  $H(1, D_\phi(X'))$
7. Update  $\phi$  to maximize  $D\_loss\_real + D\_loss\_fake$

Continue...

## Algorithm: The training procedure of MoGAN

**Initialize:** Number of total epoch  $n$ , number of Step 2 per epoch  $\alpha$ ,  
randomly initialized weights  $\theta, \phi$  for  $G_\theta, D_\phi$

**Input:**  $X = \{x_1, x_2, \dots, x_{n-1}, x_n\}$

8.  $G\_loss\_Step1 \leftarrow$  Get loss value from G for  $H(1, D_\phi(X_p + G_\theta(X_p)))$
9. Update  $\theta$  to minimize  $G\_loss\_Step1$
10. for  $\alpha$  do:
  11.  $G\_loss\_Step2 \leftarrow$  Get loss value from G for  $H(x_n, G_\theta(X_p))$
  12. Update  $\theta$  to minimize  $G\_loss\_Step2$

## ● CMD (Campus Mobility Dataset)

- Collected from the wireless network of intelligent ICT Convergence Research Center in Pangyo, Republic of Korea
- 12 APs, 289 users



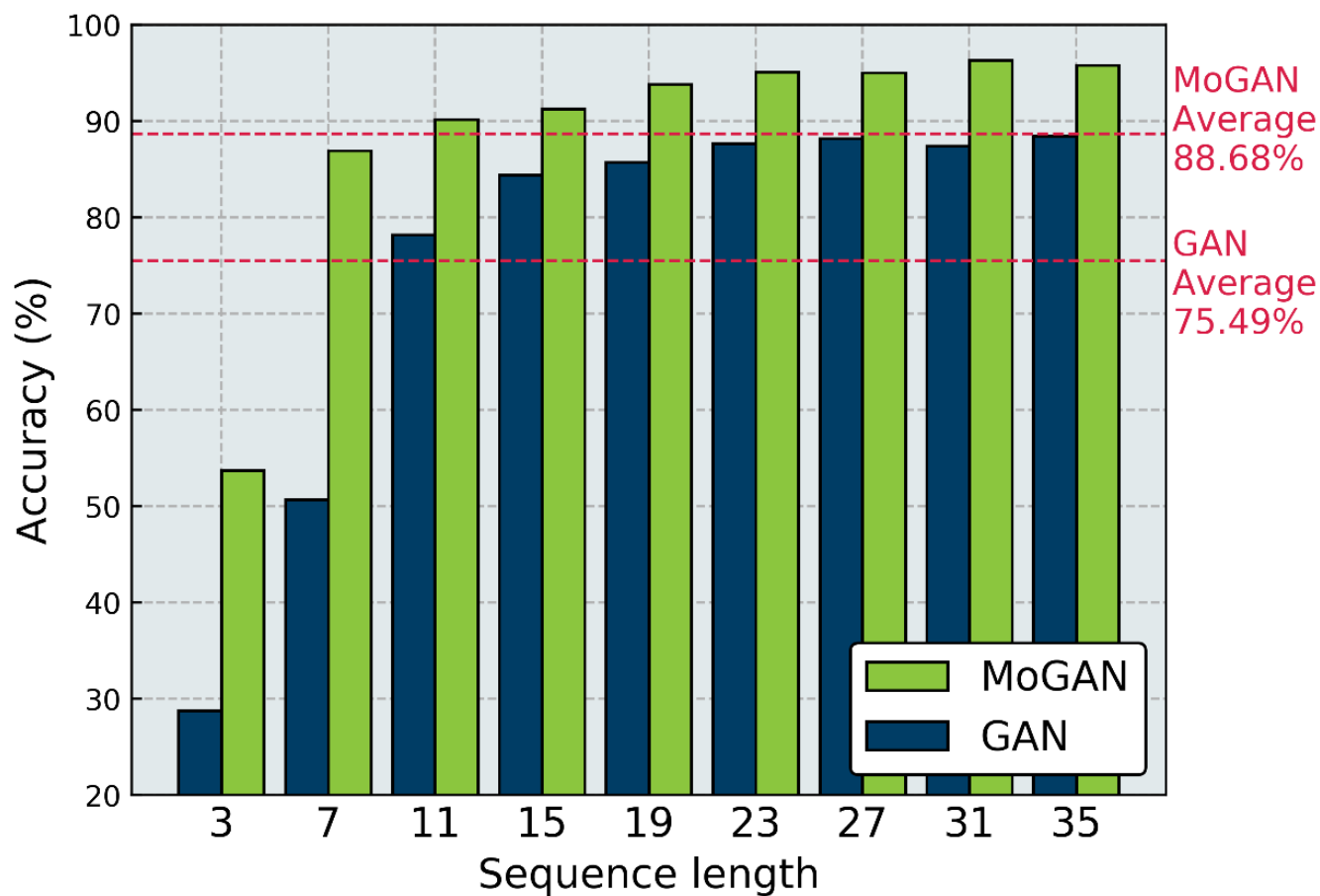
## ● Configuration

- Generator : GRU (512 nodes) + Output layer (12 nodes, softmax)
- Discriminator : FC (128 nodes, tanh) + FC (64 nodes, tanh) + Output layer (1 node, sigmoid)
- Adam optimizer (lr=0.001), 4000 epochs, 31 sequence lengths,  $\alpha = 1$
- Data → Training : Test = 7 : 3

# Evaluations



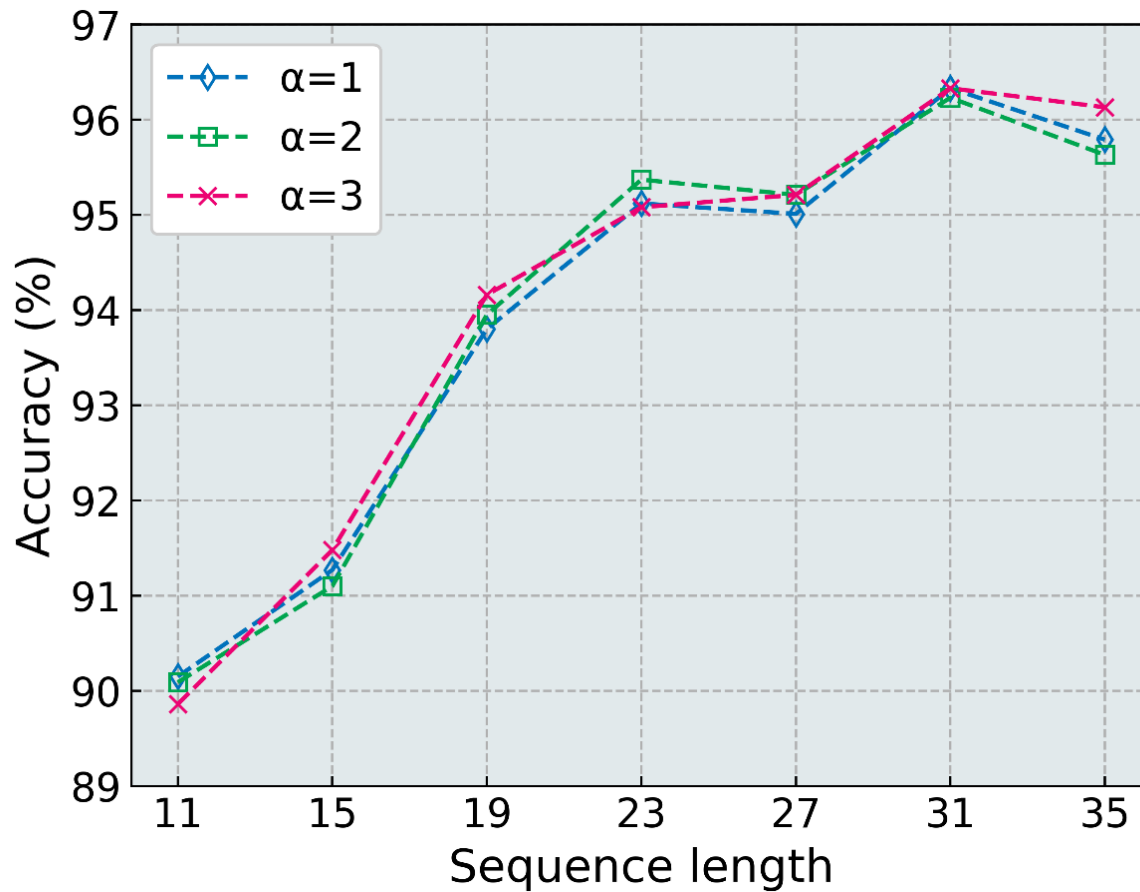
- Next PoA prediction accuracy comparison between MoGAN and vanilla GAN for different sequence lengths



# Evaluations



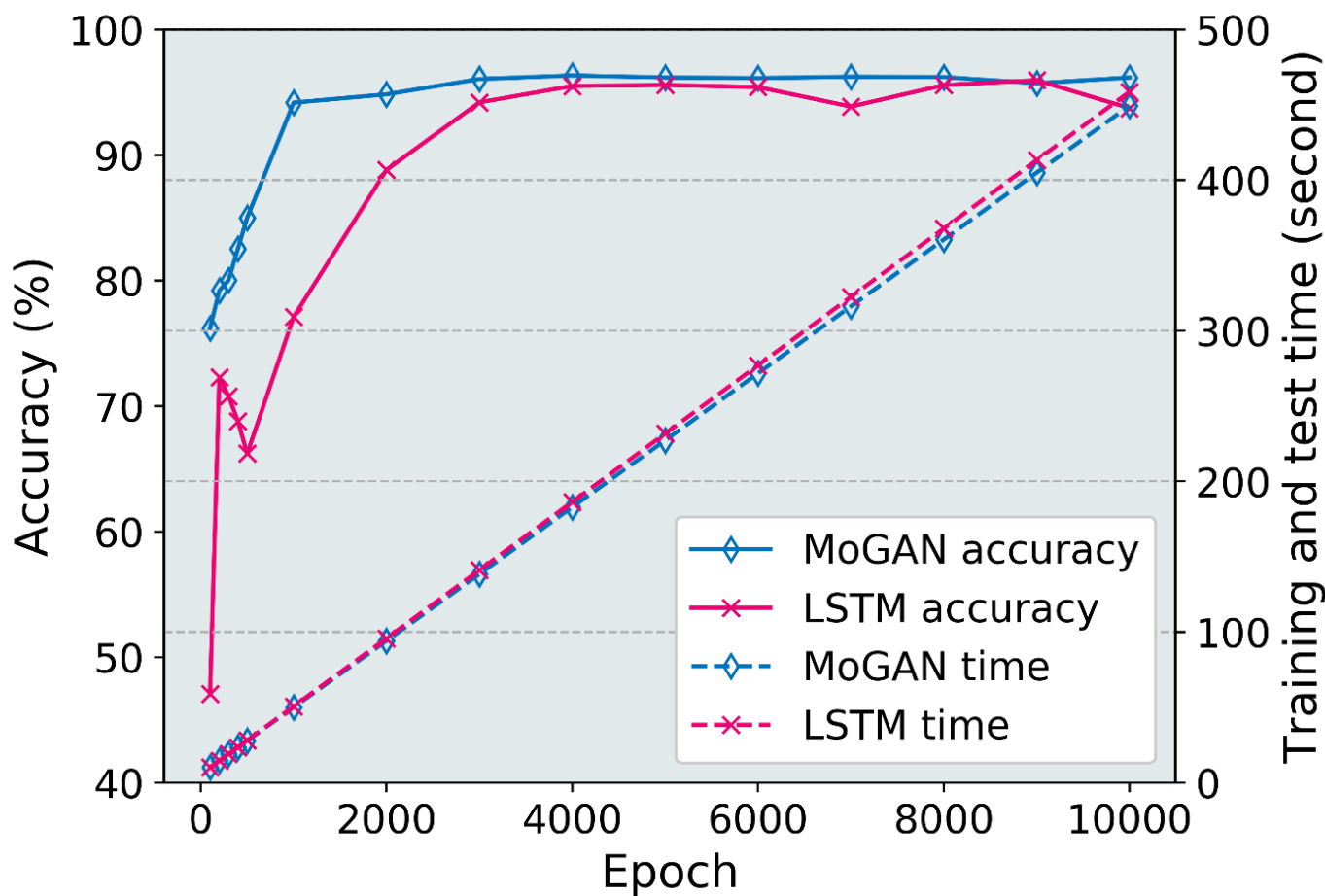
- Analysis of MoGAN with different iterations of Step 2 training ( $\alpha$ ) with increasing sequence length



# Evaluations



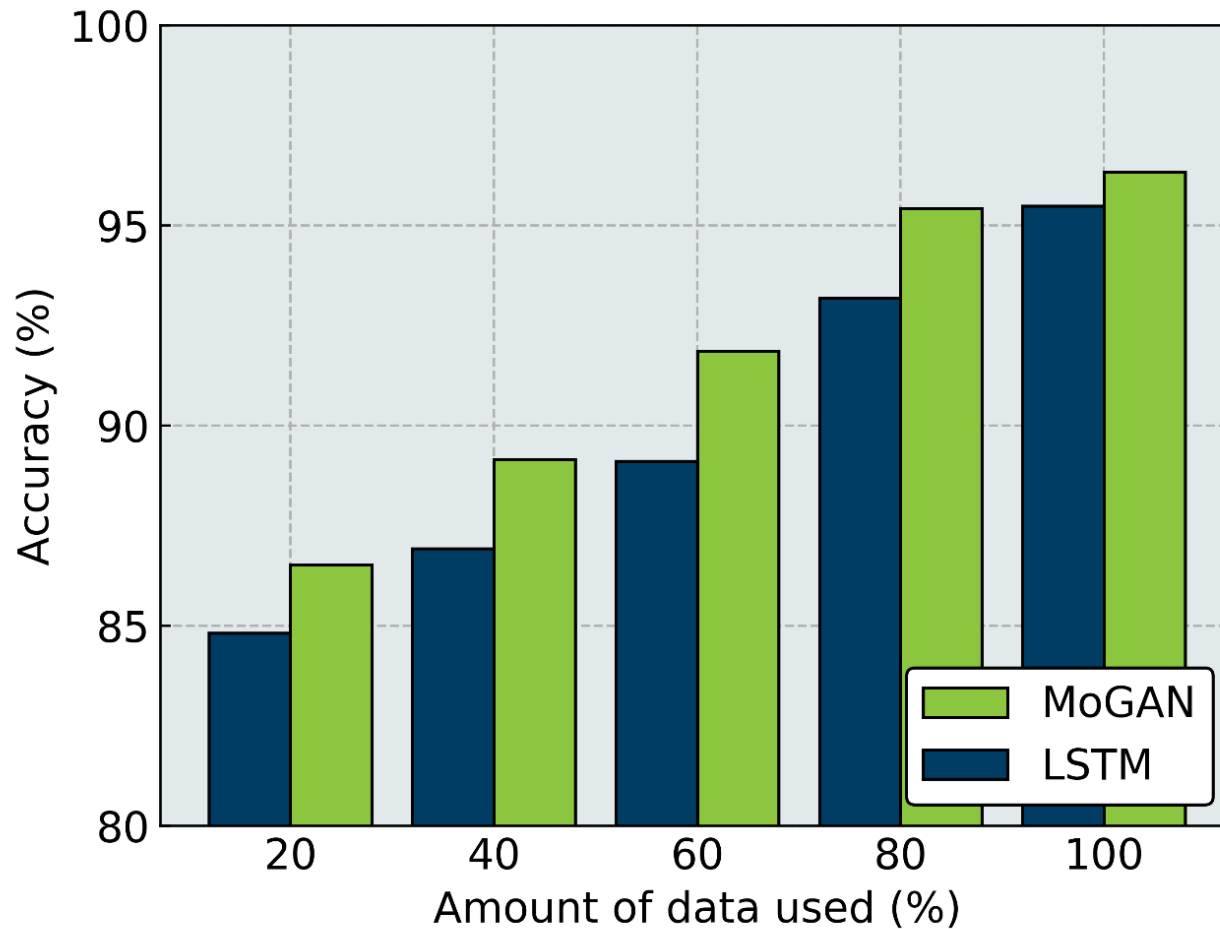
- Performance comparison between MoGAN and stacked LSTM in terms of next PoA prediction accuracy and time cost



# Evaluations



- MoGAN and LSTM performance comparison with limited data



- MoGAN achieved maximum 96.33% accuracy
  - For perspective this means that if 3,000 users perform handover at a given time, MoGAN correctly predicts next PoA for 2,890 users
  - Predicting next PoA for a user takes 5.85ms, which makes MoGAN suitable to be used in real mobile network
- Improved method for data-based prediction is suggested which can be used in other domains
- Future work
  - Improvement of MoGAN through other attention mechanisms
  - Extend MoGAN from single step to multiple step prediction

# Thank You!

